Please read this manual carefully before using the system

Use not ice:

1. On the packing, please check the system have damaged during the transit, whether the content listed on the packing list and the items in the cabinet.

2. This manual applies to Beijing STARFIRE control technology co., LTD., peak production of SF-2100S-AH NC cutting machine system.

3. Please check whether the power grid voltage is correct. Between the grid and the system to use AC220V isolation transformer, to ensure the safety of the system reliable work and personnel.

4. Numerical control system requires working environment temperature 0 $^{\circ}$ C ~ + 40 $^{\circ}$ C, relative humidity of 0 ~ 85%. Such as it works high temperature, high humidity and corrosive gases under the environment, need to take special protection.

5. CNC system wiring to correct parts, good ground contact.

6. CNC system does not allow charged plug all cable at the back of the case, the resulting consequences. Or company refused to guarantee.

7. CNC system output port at the back of the line, does not allow with other power cord short circuit, otherwise will be burned CNC.

8. Under the environment of high dust, dust the machine needs to be done protection, and require regular cleaning dust, as far as possible to ensure that the numerical control system clean.

9. NC system should be managed by personnel, should carry on the training to operators.

10. CNC system is not allowed to use inner the AC/DC power supply to connection to other electrical appliances.

11. In case of problem, please contact with the company. Don't in unfamiliar situations to tear open outfit, the transformation system.

12. The maintenance system and machine tools, daily maintenance and check once per class. Every month performs maintenance level 2.

Every six months perform maintenance level 1.

13. CNC system Settings of various parameters, we will strictly in accordance with this manual or order of added set. Such as setting parameters within the prescribed scope, or can make the operation of the CNC system and even damaged.

14. The LCD panel of the system is fragile goods, pay attention to during the process of using LCD for protection.

15. This system technical indicators in the event of a change, without prior notice.16. Note:

System's USB port output power is very small, only for the use of USB flash drive, can't pick up any other USB devices, in case of damage.

17. Special announcement:

Warranty, the warranty of this product range is from the date of delivery, 12 months, according to the instructions allow what happened under the condition of fault.

Warranty and warranty beyond the treatment of the failure is a subscription service. The following case is beyond the scope of warranty:

The following case is beyond the scope of war

A: Use breach of art ificial damage

B: The damage caused by force majeure

Force majeure usually includes two cases:

The natural causes, such as lightning, flood, drought, storm, earthquake, etc.

Another: The social causes, such as war, strikes, government ban, etc.

C: Without permission, without authorization, remove the damage caused, modification, repair, etc.

18. The interpretation of this manual belongs to Beijing STARFIRE control technology co., LTD.

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Chapter 1 System function interview

1.1 system function

SF-2100S-AH is applicable for kinds of flame/plasma cutting machine CNC system, widely used in small desktop cutting machine of metal processing, advertisement, stone material industry, etc.

The system is designed with high reliability, with plasma interference, lightning protection and surge capacity.

Practical flame/plasma cutting process, plasma processing, automatic corner speed control, and control the block.

Can use wireless remote control or wired control box to realize remote operation.

Slotting compensation function and test procedure of compensation is reasonable, the report accordingly, for the user to choose from.

Breakpoints recovery, can automatic power to restore function, also can be breakpoint memory automatically.

Function of any passage and punch point processing, can be arbitrary line escapement in machining.

Suitable for thick plate extension perforation function, and is suitable for the bypass function sheet.

Back, passage and breakpoints in recovery, to choose the function such as perforation position, greatly convenient user manipulation.

Can transfer cutting at any time, choose the starting point of processing. This can be automatically generated broken bridge.

Small segment of the special processing functions, walking is fluent, can be widely used in metal and advertisements, wrought iron, etc.

Including 24 kinds of graphics component library (customizable), contains the common basic processing parts.

With STARCAM nesting software is fully compatible with, and at the same time compatible IBE (Germany), FASTCAM in major nesting software.

Interface conversion, in both English and Chinese language. Also can be customized to other countries.

Dynamic graphical display, 1 ~ 8 times of graphics zoom. Fixed pointscan automatic tracking.

Using U disk read and software upgrades in a timely manner.

1.2 technical indicators

Processor: using industrial-grade ARM processing chip.

Display: 7 inches color LCD display, 800 * 480 resolution.

Input/output: the system to provide the number 13 photoelectric isolation input, 8-way photoelectric isolation output, including four roads relay output.

Linkage axle count: 2 axles, it can be extended to 3 axles linkage.

Top speed: < 24Meters/Min.

Pulse equivalent: flexible adjustment.

Storage space: 4G super user program storage capacity, processing program is not restricted.

Case size: 298 * 202 * 95.2 (mm).

Working temperature: 0 $^{\circ}$ C ~ + 40 $^{\circ}$ C. Storage temperature: - 30 $^{\circ}$ C ~ + 60 $^{\circ}$ C.

1.3 the company's products supporting application of CNC cutting

machine



Chapter 2 System main menu

2.1 Menu characteristics

According to operating of the system, adopt function window prompt way step by step. Under the main window menu, after a function call, system will launch this feature of the child window menu. According to the prompt of screen window, press [F1] to [F7] key on the panel to choose corresponding function. Press "ESC" to return to the next high levels menu.

	北京斯达峰控制技术有限公司										
		4	TA	RI-I	RE						
			SF-21	00S-AH							
			010-88	8909875							
			www.sta	rfcnc.cor	n						
VER:3.0-1.4	.3										
ESC	AUTO	MANUAL	EDIT	SETUP	DIAGNOSE	LIBRARY	MORE				

2.2 the main menu shows

The version number: the lower left corner tip is currently about software, hardware version information. Photos are for reference only.

- [F1] automatically: automatic process control
- [F2] manual: manual adjusting cutting gun position
- [F3] edit: edit/modify/USB input/USB output processing program
- [F4] parameters: the system parameter settings
- [F5] diagnosis: check the machine input and output information
- [F6] graphics library: standard graphics Settings and discharge
- [G] [G] [3] setting: in the following dialog:

		更新达 PARA FORM	峰控行	制技才	大有限 RE	公司		
		LANG	JAGE www.sta	irfcnc.coi	m			
VER:3.0-1.4							6191	
ESC	AUTO	MANUAL	EDIT	SETUP	DIAGNOSE	LIBRARY	MORE	



File format: formatting user space program Initialization parameters: restore before delivery preferences.

ENGLISH switch in both Chinese and ENGLISH

Chapter 3 automatic function

In the system work under the main menu, press [F1] into the function of automatic main picture:

SPEED: F005%=0 SPEED= 49	ROG: TKOO . NC P	IERCE N:0001	SPARA:3.0	M: 038	P I ERCE	CUT
			7		TORCH UP	TORCH DN
					GAS	HOTUP
					X TEST	Y AU-SPEED
					1 ZOOMIN	2 200MOUT
					F ADSPEED	G CONTINUE
					I∕₽: 880	88888
					0∕P: ○●○	000000
					ANGLE : PROPORT. :	0.00
—					BEG. ROW:	0.00
EG ISTART-NOT IME					DISTANCE::	100
X -00001.50	0 WORKMOD	E			HOTUPTIME: MACHINE X:	3.0
Y -00007.98	0 OPERATE	₩ORK.	T: 0.8		MACHINE Y: -	-00009.480
5> G1X0.000Y110.000 6> G1X100.000Y0.000					BACKWARD	FORWARD

3.1 interface automatic way specification

3.1.1 speed

In automatic mode: left upper corner of the screen shows F * (automatic processing speed ratio value) = set value processing speed.

In manual mode: left upper corner of the screen shows F * (manual speed ratio value) = manual speed.

SPEED is the speed of the actual value, use $[F \uparrow]$, $[F \downarrow]$ ratio value to adjust the current speed.

Press [F] speed setting directly on the screen, and press [enter] to confirm.

Note: the speed of the display value may be metric also can be inch, depends on the parameter settings in metric/inch option (see parameters - control).

3.1.2 procedure, perforated serial number, slotted

Respectively show the program name for processing program, the current has been perforated serial number (to be automatic processing automatically when the clearance), the current compensation slot width.

3.1.3 working mode, the operation information

Work mode bar shows: the current work status, such as choosing rotating,

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breakpoints recovery, the mirror function, parts processing, etc. Operational information bar is displayed in: machining or suspended, various limit alarm, and delay time and other information.

3.1.4 input and output

Under the switch side, two platoon x $8 \circ$ "(when the parameter" to take over control box selection "is valid for three rows of x $8 \circ$).

The above said eight input port status, ○ says no signal input, ● said signal input. Intermediate said 8 input port status, ○ says no signal input, ● said signal input. Below said 8 output port status, ○ says no signal output, ● said signal output. Input/output port definition is to see system diagnost ic function.

3.1.5 machining parameters showed

The column shows the current various parameter values.

3.1.6 coordinate unit selection

Coordinate display may be a metric (mm) can also be inch (inches), depending on the parameter settings in metric/inch selection (see parameters - control).

3.1.7 according to a panel of six heavy current key, can control the

external heavy current, including:

[Ignition] Ignition functionsees M20

[Preheat oxygen] opened oxygen solenoid valve, concrete M24

[Acetylene open] opened acetylene gas solenoid valve, concrete M10

[Cutting oxygen] opened cutting oxygen solenoid valve, concrete M12, plasma cases through arc starting switch

[Punch] high voltage control keys

Complete a piercing process, specific operation is as follows: Flame processing - the first cutting torch rises (M72), open cutting oxygen (M12), cutting down (M73).

Plasma processing - execute M07 instructions

[Skill] this is a very important function, in the later suspended is used repeatedly, the fallback, epitaxial perforation, when after the preheating, press "punch" directly, can make the punch starts with one.

[Always shut] close all high voltage output.

 $[S \uparrow]$ press cutting up, lift the stop.

 $[S \downarrow]$ press cutting down, lift the stop.

3.1.8 [1] enlarge figure

Press one graph 1 x magnification. Press 3 times in a row, graphic maximum amplification eight times;

3.1.9 [2] to restore

Reconstruction to the standard image size

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3.1.10 [X] empty running

Press "X" button, the system for processing speed limit to run the program, but does not perform M instructions. This feature is used to quickly locate, or check the steel plate processing. May at any time in the operation of the suspension, and then press "X" key to cancel empty running.

3.1.11 [Y] speedprocessing

Speed system in manual and automatic speed is separated, push down this button (highlighted), adjust the speed for automatic processing in the process of speed ratio, vice to manually adjust the speed ratio.

3.2 the function option of automatic processing

Processing program can be transferred to file by editing function, if the program has been transferred to (same as long as the program name), can be directly run. If is to use U disk transfer into the program, especially large program, you cannot for storage, with the U disk processing run directly.

3.2.1 [F1] punch points

Specified from starting the random program (or perforation) arbitrary processing. Commonly used in the need to start from the application of a certain period of processing, or only used when processing a part of. Specific see passage function.

3.2.2 [F2] manual

System turns to the manual work mode.

3.2.3 [F3] find breakpoint

Select this function, press "start" button to start implement breakpoints recovery function, specific see breakpoint recovery feature.

3.2.4 [F4] graphics

SPEED:F005% SPEED= 0	=• PR	DG : TKOO . NC	PIERCE	0000	SPARA:3.) <mark>M:</mark>	PIERCE	CUT
					1		TORCH UP	TORCH DN
							GAS	HOTUP
							X TEST	Y AU-SPEED
							1 ZOOMIN	2 200MOUT
			-				F_ADSPEED	G CONTINUE
							I∕₽: 000	88888
							0∕P: 000	00000
							ANGLE : PROPORT :	0.00
							BEG. ROW:	0.00
							DISTANCE::	100
X - 0.0.0	01 500	WORKM	0 D F				HOTUPT IME :	3.0
V 000	190 199			то			MACHINE X:	00003.244
			LL AU				THEFTIL I.	
ESC	N-PIERCE	STARTP		Ų	IEW			INFORM

Select this function, the system display graphics processing procedure, and marking punch points are numbered sequentially, graphics origin points have cross cursor. Press [1] 1 time magnification graphics (up to three times, enlarge 8 times), press [2] graphics recovery, according to the $[\uparrow][\downarrow][\leftarrow][\rightarrow]]$ key mobile graphics display position.

3.2.5 [F5] set slot

Click this button prompts for slot width compensation, if you don't compensate (usually in the nesting compensation) can enter 0.

3.2.6 [F6] auxiliary function

SPEED:F005%=0 SPEED= 0	PR	IG : TKOO . NC	PIERCE N:	0000	SPARA:3	.0 N:	PIERCE	CUT
							TORCH UP	TORCH DN
							GAS	HOTUP
							X TEST	Y AU-SPEED
							1 ZOOMIN	2 200MOUT
			-				F ADSPEED	G CONTINUE
							I∕P: 000	388888
							0∕P: 000	00000
							ANGLE :	0.00
							PROPORT.:	1.0
							BEG. ROW:	0.00
							DISTANCE::	100
X - 0000	11 500	WORKM	O D F				HUTUPTIME:	3.0
V 0000	0 100			0			MACHINE X:	00003.244
1 0002	122	UPERA		0			MACHINE Y:	00027.622
ESC	CONTOUR	WENTAI	ROTATE	M	IRR	SCALE	NEST	BRAKE

Press [F6] key to enter the next level menu, shown in figure , the following:

3.2.7 [F1] contour line function

SPEI SPEI	D:F005% D= 0	=• PR	OG:TKOO.NC	PIERCE N:	0000 SPARA:	3.0 <mark>M</mark> :	PIERCE	CUT
							TORCH UP	TORCH DN
							GAS	HOTUP
							X TEST	Y AU-SPEED
							1 ZOOMIN	2 200MOUT
				*			F ADSPEED	G CONTINUE
							I∕P: 888	388888
							0/P: 000	000000
							ANGLE :	0.00
							PROPORT.:	1.0
							BEG. ROW:	0.00
							DISTANCE::	100
y	0.0.0	00 000	WODEL				HOTUPTIME:	3.0
	000		WURKN				MACHINE X:	00003.244
Y	000	000.000	OPERA	IE AUT	0		MACHINE Y:	00027.622
ESC		CONTOUR	WENTAI	ROTATE	MIRR	SCALE	NEST	BRAKE

The user before processing, can be determined by taking the contour line, the machining path is beyond the scope of the steel sheet.

Press [F1] key to start walking contours, if not on the current torch reference point (coordinates not zero), the system will prompt:

The current point positioning --- will torch the current position as a reference point. Reference point location --- torch to return to the reference point, and then began to walk contour.

When walking contours, if the torch over the range of steel, according to the [Pause] key to move the position of the torch to the plate edge, then press [Start] button, then the system prompt: Modify the reference point "EN / ESC?" Press Enter to confirm the reference point if changed, the current location will continue to operate as a contour line. Press [ESC] to abandon changes. This operation can be repeated many times do run until the position you prefer.

3.2.8 [F2] WENTAI

Press [F2] button, the system prompt processing WENTAI program, WENTAI is a word processing of CAD/CAM software, cutting of calligraphy in the advertising industry process, there are a wide range of applications. If processing WENTAI generated program, need to choose this functionality.

3.2.9 [F3] rotation (steel plate correction function)

3.2.9.1 rotation angle processing

Processing steel plate lifting is impossible once, or for other reasons need to rotate an angle processing, can choose the function. Can cooperate [manual] -[supplementary] –[starting point measurement] and [measuring the finish]using rotating function. Also can be directly input Angle. After confirmation, the system will reduce the machining procedures according to the specified Angle rotation. Note: a positive perspective to counterclockwise.

3.2.9.2 example:

By measuring the an edge of the plate (a line) as the starting point and end point, calculation of rotation Angle, as follows (the following is done in the manual - auxiliary mode):

First determine baseline, take a plate from the sidelines do baseline, move the cutting torch to baseline starting point, press [F3] set the starting point. Control cutting along the baseline to the end (starting point and end point more far more accurate), cutting gun aimed at baseline, press [F4] set the end point. When relative to baseline rotation Angle are calculated automatically, complete rotation function, rotation Angle display in operation information bar.

3.2.10 [F4] mirror

Continuous press [F4] mirror respectively select X, Y, mirror, cancel the mirror. Choosing X mirror, along the X direction of axisymmetric process execution, looks like a turnover on the up and down.

Choosing Y mirror, along the Y direction of the axisymmetric execution process, looks like a turnover.

3.2.11 [F5] proportional

Press this key system prompts for scaling, system application, enlarged or reduced according to the proportion, this feature is useful to hand art by in the process of cutting.

3.2.12 [F6] discharge function

For a single process that has programmed, can through this function arrangement processing.

System prompt:

Arrangement of rows - Y direction to arrange the number of rows Arrange the number of columns - the column number of the X direction is arranged.

Line spacing - spacing between the X direction of the workpieces. The gap between the column spacing - Y direction of the work pieces

Line offset - the even lines, migration distance to the right.



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3.2.13 broken bridge function

Choose this feature, during processing, every cutting length (broken bridge point. Mm. See [parameter] the [control]), will set up a bridge cut-off point, partition bridge length (MM) (see [parameter] the [control]) controlled by the operator to continue after cutting. Note: this function has remained until then click this button to cancel the function.

3.3 automatic startup

3.3.1 cutting speed

When machining, the automatic speed ratio adjustment.

The speed of execution = machining speed limit * ratio, $[F], [F^{\dagger}], [F^{\dagger}]$ is automatic rate adjustment. The two speed ratio once set, it is forever, is not affected by the shutdown.

3.3.2 automatic machining start

1) Before automatic machining start

To choose the correct processing program, select the appropriate processing rate (ratio), the cutting torch on the cutting height (after the start process, automatically cutting torch lift (execution M70)), and other preparations in place, can start the process automatically.

2) There are two ways of automatic processing start:

According to the green "start" button on the panel.

According to external "start" button (see "input and output port definitions")

3.4 adjustment of cutting position of automatic control

3.4.1 track in the process of automatic processing begins, only the

following keystrokes effect ive:

[Pause]: press this button, the system movement slowing down to stop, close cutting oxygen (plasma processing, shut off the ignition switch), closed higher controller (M39), keep the currently displayed image. If you choose in the parameter is set to "suspended after raise gun (1)" (see control parameters), suspended after cutting torch will lift (M70).

SPEED: F100×=4000 SPEED= 0	ROG : TKOO .NC P	IERCE N:0001	SPARA:3	.0 M: 013	P IERCE	CUT
			7		TORCH UP	TORCH DN
					GAS	HOTUP
					X TEST	Y AU-SPEED
					1 ZOOMIN	2 ZOOMOUT
					F ADSPEED	G CONTINUE
					I∠P: 000	388888
					0/P: 000	000000
4					ANGLE :	0.00
					PROPORT.:	1.0
					BEG. ROW:	0.00
EGISTART-NOT IME					DISTANCE::	100
V _00001 500		E			HOTUPTIME:	.23
	WUNKMUU				MACHINE X:	00001.744
Y 00009.896	<u> OPERATE</u>	PAUSE.	T	: 0.8	MACHINE Y:	00037.518
5> G1X0.000Y110.000 6> G1X100.000Y0.000		NEX	T LINE	N-PIERCE	BACKWARD	FORWARD

After suspended can be the following:

a) Select new piercing point, press "F5" key to enter the new perforation after a period, the system automatically go to the new perforation, waiting for the punch operation.

b) The original track back.

c) Press "F4" button, select the line escapement operation, the system prompt: fallback, forward and choose program line, according to mark new selected row cursor position operation, press the "start" key, the machine go to the new line escapement position, waiting for the punch instruction to continue processing.
d) Adjust the position and so on.

e) Exit processing.

f) [Start]button: systems continue to run.

g) [ESC] key: Exit the machining program, return to the automatic image.

h) **[F**], **[F**] speed adjusting button: increase or decrease feed speed ratio.

i) $[S \uparrow]$, $[S \downarrow]$ control cutting torch up and down. Press the corresponding key, cutting up or down. Raise my hand cutting movement to stop.

j) [Stop key]: Scram button for external key (see the [external input interface]), the signal from the input port access. When stop is valid, and stop all movement, output shut down, for unexpected emergencies. Due to the conditions of the suspension system and the following points:

1) The external pause button press.

2) Plasma processing, and choose the "arc pressure test (1)", if the broken arc will be suspended.

3) If you choose "" bump shot detection (1)", efficiently gun will be suspended.

3.4.2Pause after the adjustment of position of the cutting

3.4.2.1 the following several ways of cutting torch position need to

adjust:

1) Cutting torch is blocked, or need to change, often move the cutting torch to a safe location, after processing to return to the starting point.

2) Need outer perforation, don't want to put the punch points on the outer limits of the machining. In the workpiece outside to look for a suitable position (usually the edges of the plate), perforation and then cut along a straight line to the starting point (pause) continue to normal processing.

3) Transfer of cut, work piece is bigger, wide is bigger, need to change the local cutting.

3.4.2.2 several operating can adjust the cutting position of the

following:

(1) Suspension

(2) The fallback

(3) Punch

(4) Parts processing

(5) Machining

(6) Breakpoint recovery

In the state, if want to change the cutting position, can be directly according to the $[\uparrow] [\downarrow] [\downarrow] [\downarrow] [\downarrow] [\downarrow]]$ key to adjust the position of the cutting torch (the system ratio for manual rate can be adjusted). After adjustment in place, press the [start] key, the following dialog:



1) Return to the original road

To return to adjust starting point with the speed of G00, in this waiting for further operations. At this point according to the corresponding high voltage function keys (such as ignition, preheated perforation, open cutting operations such as oxygen). Suggestion: after preheating, and then press [punch] key, then the system starting from the breakpoint position to continue processing.

2) Cutting back

First perforation, again with cutting speed along a straight line from the current position to adjust the starting point, don't stop according to the original path to continue processing, a bit like epitaxial perforation, perforation point more smooth.

3) Current perforation

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Perforation first, to adjust the current coordinates to suspend the coordinates, according to the original path to continue processing, in order to realize the transfer function of perforation.

4) Note: before operation 2) and 3), should be fully preheat (fire),

because once chose operation, punch right away. Normal practice should be first preheating (fire), then to press the [start] key.

3.5 the original track back processing

For failing to cut through, in the processing to the original track back, is as follows:

3.5.1 Track of the original track back, press [pause], slow down the

running system, the system displays "pause" tag, and presented the

following figure.



Press "F6" key system to perform the original track back, back speed set in the parameter - speed - back.

Press the "F7" key at the back, on the basis of the original trajectory. In the process of back, if do not meet the need of position, can press the pause again, repeat the above process, until a bit.

3.5.2 encounter G00 (reach a piercing point) back in the process.

When back, meets G00 (reach a piercing point) suspended system, the operator can choose is to continue to back, or forward.

3.5.3 back to operations

Back to the designated place, can choose cutting torch position adjustment, (see 3.4), may also directly bring a perforation, according to the corresponding high voltage function keys (such as preheating perforation, open cutting operations such as oxygen). Typically:

Good for preheat, then press "punch", in the case of fire, burning torch, oxygen cutting, cutting down, the system to continue running, under the condition of plasma arc open, wait for after the arc, the system to continue running.

3.5.4 Above operation can be repeated, until get the desired effect.

3.5.5 exit processing state

Press "ESC", during a break in system processing status.

3.5.6 fallback procedure of the total number of rows and the starting

line Fallback procedures section, most within the 300 lines, if it is a

breakpoint recovery, or parts of the processing, the back of the starting

line is the current breakpoint or passage, not on the basis of rolling back

processing.

3.6 breakpoint recovery and double breakpoints recovery processing

3.6.1. Breakpoints recovery

1) In the system for suspension or for processing power failure, the system will automatically save the current cutting torch position for a breakpoint. The breakpoint will be permanent, whether to turn it off or not.

2) When in automatic mode, as long as the current program did not change, can press "F3" find the breakpoint function, then press "start" button, system breakpoint began to recover.

3) If the cutting position has not changed, then find the breakpoint, prompted to "break", waiting for the next step. User can choose directly [perforated] cutting position adjustment, see 3.10.

4) If the cutting position have changed (not on the breakpoint), after the system find the breakpoint, can appear the following three options (The fact is the cutting position adjustment).



The original road return -- to return to the breakpoint with the speed G00, commonly used in general (exchange) cutting set breakpoints.

Cutting back -- a breakpoint recovery can be slightly left point breakpoints, a bit like the outer perforated, make breakpoints more smooth;

Current punch -- like the previous operation, transfer can also be used to cut with. At this point according to the corresponding high voltage function keys (such as ignition, preheated perforation, open cutting operations such as oxygen).

Tips: After preheating, then press "punch", then the system starting from the breakpoint position to continue processing. When it finds a breakpoint, press "ESC" key, system exits the processing status.

3.6.2 double breakpoints recovery feature

System can save two procedures that face the breakpoint. Operators do a larger

program A, the intermediate temporary stop (generated the first breakpoint), to do another program of B. After the call the program A again, can be directly do restore ((find the breakpoint)) breakpoint, the system will automatically find the location of the interrupt for the first time, to continue processing.

3.6.3 note:

Both breakpoints recovery and restore power, are not allowed to change the Angle of rotation, scaling, the condition of the system will automatically save, not affected by the switch machine. Otherwise the system may find the breakpoint.

3.7 parts of choose

3.7.1 start the parts choose

Parts of functions specify system, from the program (point) or a perforation arbitrary start processing.

3.7.2 select parts processing there are generally two kinds of situations:

3.7.2.1 transfer processing. It starts from a certain position in the

program, in a place to start processing.

3.7.2.2 will start a paragraph from the program after program to

processing it again.

1) For the former, usually find a piece of waste, on the punch point directly processing (optional, the current point positioning).

2) In the latter case, the orientation from the reference point (optional, reference point positioning).

3) For the two options, the system that after the boot prompt (below):

A) If you select "current point positioning", after the system is running, the first map, and on to the position of the punch, draw a big cross cursor, the operator can press [S] graphics to enlarge, to see whether to need to punch positions, if not satisfied, can press "ESC" to exit the processing state, select again.

B) If the requirements of the perforation point, can be controlled by high voltage

switch, ignition, preheating, press "punch" up and running;

C) If you select the "reference point" to start, the operator should aim the cutting torch reference point. After start-up, the system control cutting punch point and the rest of the operating methods.

3.8 the edge of the thick plate perforation

1) Automatic processing of the thick plate processing method should be used when perforation.

2) Edge of the perforation of the method is: Before punch cutting torch to move to the edge of the plate recently.

3) Start preheating, when after the preheating, press the "start" key, cutting along a line distance and the selected cutting speed cutting to punch, cutting processing again.

4) Uses the edge notch, the first change parameter control menu of edge notch choice to 1 (said to choose effective). So every hole, the first prompted the diagram below:



3.8.1 select perforation the current position

Perforation system the original position, commonly used hole.

3.8.2 perforation the selected edge

(1) The operator may according to the selected [up] [sown] [left] [right] key, adjust the position of the cutting torch to the outer limits of the steel plate (the speed ratio automatic adjustment for 5%), start preheating.

2) When the preheating ended, press the "start" key, cutting along a line distance and the selected cutting speed to punch, cutting processing again.

3.8.3 choose don't punch

Don not punch, the system runs directly from the current perforation position. Blank line to the next hole, a new perforation tips.

The fourth chapter Manual function

System work under the main menu, press "F2" button to enter manual

function, as shown in the figure below:

SPEED : F018% SPEED = 0	=704 PR	<mark>dg : t</mark> koo .nc	PIERCE N:	0001	SPARA:3	.0 M:	P IERCE	CUT
							TORCH UP	TORCH DN
							GAS	HOTUP
							X TEST	Y AU-SPEED
							1 ZOOMIN	2 ZOOMOUT
							F ADSPEED	G CONTINUE
							I∕₽: 880	388888
							0∕P: 000	000000
							ANGLE : PROPORT :	0.00
							BEG. ROW:	0.00
							DISTANCE::	100
X AAA	132 561	WORKM					HOTUPTIME:	0.07
Y 0.00	103 716	OPEBA	TE MAN				MACHINE X: MACHINE Y:	00034.306
100		OTEN		MA	011.0	II ODED	01.0 00	DEWLIDM
F2C	HUTU	SIEL	UTHERS	MA	UH-V	H-9RED	012-00-	RETORM

4.1 manually interface manually interface display with automatic mode.

Difference in the value of the ratio of the manual, it affects the manual operation, back to the speed, movement speed, etc. Directly on the screen press [F] speed can be set. There are some special operation manual modes.

4.1.1 [up] [sown] [left] [right] the direction control keys and [G]

continuous walk normally, press the four direction key, the corresponding axial movement, raised my hand against the stop. But according to [G] choose walking straight (highlighted), press the direction key cutting start (Raise hand stop), press the stop again. If need two axis at the same time, can walk on a shaft, another axis of the direction key, press the two axis movement at the same time. Press any key direction at this time will stop cutting torch corresponding axis, and the rest of the shaft to continue walking, walking until then press the axis direction, movement stops. [Pause] button will also stop movement.

4.1.2 "F1" automatically

System into automatic working mode

4.1.3 **[F2]** inching

Press "F2" button, click on, appear some dynamic incremental selection dialog. Point move incremental there are four choices: The first three are commonly used incremental. Finally a press 3 - input increment is

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manual input increment. In inching mode, press a key direction, cutting at the speed of the current highest speed limit by ratio, run a point incremental value.

4.1.5 [F3] high speed

Quick select manual ratio, press F5 high-speed (highlighted) ratio is 80%, then 10% at low speed.

4.1.6 "F4" clean coordinates

Quickly reset X/Y values.

4.1.7 speed at the upper left screen display F * (manual speed ratio

value) = manual speed. Directly on the screen press [F] speed setting,

and press "enter" to confirm.

4.1.8 "F8" auxiliary

Login into the auxiliary functions, the system shows the following interface.

SPEED SPEED	:F018% = 0	⁼⁷⁰⁴ PR	IG : TKOO . NC	PIERCE N:	0001	SPARA:3	.0 M:	P IERCE	CUT
								TORCH UP	TORCH DN
								GAS	HOTUP
								X TEST	Y AU-SPEED
								1 ZOOMIN	2 ZOOMOUT
								F_ADSPEED	G CONTINUE
								I∕P: 000	88888
								0∕P: 000	00000
								ANGLE :	0.00
								PROPORT.:	1.0
								BEG. NUW:	100
			- W					DISTRICE	0.07
X	000	32.561	WORKM	I O D E				MACHINE X:	00034 306
Y	000	03.716	OPERA	TE MAN				MACHINE Y:	00041.234
ESC				P-START	P	-END	COORD I-	MEASURE	ORIGIN

4.1.9 [F3] starting point, "F4" measuring the finish line, steel sheet

processing calibration function

Steel sheet is impossible once, assembly, or for other reasons need to rotate an Angle processing, the choice of this function. Will be cutting down the side of steel plate in a straight line (as long as possible) to choose two dots ([F3] test starting point and end point "F4" test). The system will automatically calculate the rotation angle. To choose of the rotation function of the automatic processing input angle. After confirmation, the system will reduce the machining procedures according to the specified angle rotation.

Note: a positive perspective to counterclockwise.

4.1.10 "F5" set coordinates

There are three options: click this button reset all coordinates, set the current coordinates, it is set to the reference point coordinates.



4.1.11 "F6" origin and "F7" reset

Machine back to the origin can be divided into "measuring the origin" and "reset" two parts.

Machine back to the origin, is the process of return machine mechanical zero point, back to zero biaxial running at the same time, independently back to zero. Reset (before back to zero):

(a) Mechanical origin should choose NPN hall proximity switch (normally open, the signal is low), and install in a suitable position.

(b) Set parameters (see parameter F3) reset speed - see "parameters" - "speed", reset when the feed rate, the unit is mm/min. reset direction - see [parameter] - [system], 0 - the shaft no longer, 1 – reverse, 1 – positive.

(c) Machine back to zero point process is as follows:



(d) To measure the origin, to determine the mechanical origin of the work piece coordinate system. Methods:

Cutting torch will be moved to the reference point in the work piece coordinate system (a bit). set the current work piece coordinates.

[manual] - [supplementary] –[origin] measurement system to complete the mechanical origin, and the current coordinate values into the origin of the machine tool value, parameter Settings [system] option in the origin of the machine tool change accordingly.

(e) Reset - cutting back mechanical zero, and set up the work piece coordinate

system.

Method: [manual] (or [automatic]) – auxiliary – reset, origin system to complete the mechanical action, and the origin of the machine tool is set to the current coordinates of the machine tool coordinate set to 0.

[note] : If two axles in the parameter reset direction from 0, namely no reset action, execute reset after operation, the current value is equal to the origin of the machine tool. Machine tool coordinate is equal to zero, this is important, because the program limit is machine tool coordinate as a benchmark. Cutting torch will be moved to the first mechanical origin (the origin is not necessarily true), select reset function, can determine the current machine tool coordinate (zero), then according to the distance from the effective on both sides of the mechanical origin, fill out the positive/negative limit value of the software. Chapter 5 editing function

In the system under the main menu, press "F2" to enter editing menu,

as shown in the figure below:

当前路径(系	统): 🔪						
0000:							
0001:							
0002:							
0003:							
0004:							
0005:							
0006:							
0007:							
0008:							
0005.							
0010.							
0012:							
0012:							
0014:							
0015:							
0016:							
0017:							
0018:							
0019:							
723	NEL	TUAD	SAUE	DFI-FILF	DFL-LINF	IISB	ITEM
EQ0	TILW	LOID				000	VITM

5.1, editing menu description

5.1.1 [F1] build

To build a new program, the clearance process editor area, and start editing a new processing procedure.

5.1.2 [F2] call in



Transfer into the program, select the call in the user program in the program, the system will be an existing program, displayed in a tabular form, and the cursor stays on the program name. Move the cursor keys to select different programs. After press enter, the selected program loading process editor area. If you press "F7", graphic displays of the program. Press "ESC" to give up to function.

5.1.3 [F3] storage

Stored program, editing procedures for storage, the system hint: enter the program name: 1234. TXT

System shows the current program name, can be modified. If press the return key, to edit the program, to select the name of the deposited in the program area, if press the "ESC" key is stored program.

Note: the program name and extension shall not exceed 12 characters.

5.1.4 [F4] delete files

Choice of to delete user program in the program.

5.1.5 [F5] delete line

When program to edit out the entire line, increase the speed of editing.

5.1.6 [F6] USB

Transmission procedure, the system supports USB transfer procedures. After press "F6" key to enter the next level menu below:



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[F1] input To send U disk program to the system process area.

[F2] output After the system processes program, output to the U disk in the program area.

5.1.7 [F7] graphics

When you want to preview the currently selected program file processing by the graphics, can press F7 key.

Chapter 6 instruction system

6.1 programming symbol shows

That action of every step of numerical control processing, is carried out according to the prescribed procedures, each process is composed of several instruction period, each instruction, and consists of several functional characters, function of each word has to be made by letter, followed by the parameter values.

Function word definition:

- N instruction period of serial number
- G preparation
- M auxiliary
- T tool functions (in this system refers to the flame width)
- L cycles, delay time
- X X axle (diameter) absolute coordinates
- Y Y axle absolute coordinates
- I arc processing, center coordinate values minus the X axle starting point value
- J arc processing, center coordinate values minus Y starting point value
- R arc radius specified
- H high arc string specified
- A secondary variable
- F processing speed, used for G01, G02, G03.

Note 1: in the introduction to the following, have agreed as follows:

X [U] n, signs X or U, n is a number, but one can only appear. By the same token, the Y [V] n - can be Y or V, n is a numeric value, also can appear one. PPn - said combination can be any axis, containing at least one axis, also can contain two axes.

Note 2: instruction execution order, and the execution of a program in

the program before the next. Within the same program instructions is before G M, S, T.

6.2 coordinate system

The numerical control system adopts standard rectangular coordinate system, the following figure:



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6.3 G (Basic preparation instructions)

(1) G92 reference point setting

Set program is running, processing starting point (reference point) coordinates, must start in the program, and set the absolute coordinates.

Format: G92 XnYn

If not after G92 with X, Y, with the current X, Y coordinates of reference points. In commonly when used machine tool positioning, G92 not with X, Z content.

2) G90 / G91

G90 absolute coordinate system (default)/G91 Relative coordinate system When using G90, X, Y coordinates, U, V relative amounts of the current point. When using G91, X, Y, and U, V are relative to the current point relative amounts. Format: G90 Format: G91

Example 1:

G92 X0 Y0 G91 / / relat ive coordinates G00 X100 Y100 / / quick positioning to (100,100), quite G00 U100 V100 G01 X500 Y100 / / linear processing to the position (600,200), quite G01 U500 V100

Example 2: G92 X0 Y0

G90 / / absolute coordinate system, but the default G00 X100 Y100 / / quick positioning to (100,100) G01 X600 Y200 / / linear processing to (600,200)

3) G20 / G21 imperial/metric shows

G20 imperial explains, the G20 after the X, Y, I, J, R, U, V, H, F, all are English unit. G21 metric specification (the default), G21 after X, Y, I, J, R, U, V, H, F, are all metric units.

Format: the G20 Format: G21

1) G00 point exercise

This directive can be realized fast feed to the specified location. When two axles have a displacement system use the highest speed ratio, linear motion from start to finish. When G00 movements, was influenced by speed ratio. Format: G00 X [U] n Y [V] n

Or: Y G00 PPn.



2) G01 linear cutting

This directive can realize tool linear feed to the specified location, as cutting movement instruction, can be single axis or two axles linear interpolation motion. Feeding speed can be specified by F command.

Format: G01 X [U] n Z [W] n [Fn] Or: G01 PPn (Fn)



3) G02 / G03 arc cutting

This instruction is applied to circular arc interpolation. Instructions are divided into smooth arc G02 (clockwise), inverse arc G03 (counterclockwise). Good or poor in the direction of the Settings below:

Format: G02 [03] X [U] n Y [V] n ln JN [Fn]. Or : G02 [03] X [U] n Y [V] n Rn (Fn) G02 [3] PPn ln Kn (Fn). Or: G02 [03] PPnRn [Fn]



EG(G02): G92 X0 Y0 G00 X40 Y50 G02 X160 V0 160 J20 G28 M02EG (G03): G92 X0 Y0 G00 X40 Y50 G03 X160 V0 160 J20 (Or G03 X160 V0 R63, 25) G28 M02

Description:

I and J are for the X, Y axles relative to the starting point of the incremental value of circle center (starting point).

R is for round radius (R positive, when arc 180 ° or less can be used to describe the radius R). if specified I, J, R. If R, don't use I, J.

4) G04 pause/delay orders

This directive is used to set the time delay, when the program execution to this directive, the program according to the L time delay, in seconds.

Format: G04 Ln

Example: G04 L2.4 (2.4 seconds delay)

During the period of execution of G04, press the "start" key is terminated latency, continue to implement G04 after application, press "exit" key to terminate the current execution.

5) G26, G27, G28 return reference point

This direct ive tool can be realized automatically return reference point.

Format:

G26 X returns to the reference point

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G27Y returns to the reference point

G28 X, Y axles at the same time to return to the reference point Example: G28 (X, Y axis at the same time to return to the reference point, equivalent to go G00)

6) G22 / G80 loop statement

This directive can be used to execute a program cycle, G22 as the beginning of the loop body, and specify the cycle number L. G80 as end of the loop body mark, this directive can be nested loop, but not more than 5 layers. G22 with several recent G80 downward constitute a loop body.

Format:

G22 Ln (L designated cycle)

The loop body G80 (end of the loop body signs)

For example:

N000 G92 X100 Y100 N001 G00 X60 Y80 N002 G22 L5 - the first layer of circulation. N003 G00 V50 U - 25 N004 G22 L5 - the second loop begins N005 G01 U5 V - 10 N006 G80 - the second end of the cycle. N007 G80 - the first layer loop ends. N008 G28 N009 M02

7) Tool radius compensation statement (G40, G41, G42)

Format: G41 (or G42) Rn.

Need to compensation procedures section. G40

Note:

G41 is for the processing of path, the compensation to the left half of the flame diameter.

G42 is for the processing of path, the compensation to the right half of the flame diameter.

G40 is for end of migration.

Because of the cutting tool compensation is done automatically, so before G41, G42 instructions must be G00 rapid positioning statement, in order to make sure the cutting nozzle can adjust the position. After cancel the knife repairing G40, still need to have a G00 statement position to adjust back.

6.4 M auxiliary function

M00 pause command, suspend execution program, press the "start" key to continue.

 $\mathsf{M02}$ instruction program ends, after the execution process in the wait state $\mathsf{M30}$ same as $\mathsf{M02}$

M10 / M11 gas (acetylene) valve switch, M10 (open), M11 (close)

M12 / M13 cutting oxygen valve switch, M12 (open), M13 (off)

M14 / M15 cutting torch switch, M14 (open), M15 (off)

M16 / M17 cutting torch switch, M16 (open), M17 (closed)

M24 / M25 standby switch, m2-m24 (open), the M25 (closed)

M20 / M21 ignition switch, M20 (open), M21 (closed)

M07 fixed cycle perforation (after entering M07, not back, can move gun) M08 concerns cut fixed cycle

Flame cutting operating sequence is as follows:

M07

1. If gas (acetylene) valve is not open, open (acetylene) gas ignition.

2. Cutting down (cutting down latency, see M71).

3. Preheat the oxygen valve, began to preheat time delay, if the preheating time is not enough, can press [pause], preheating time delay automatically extend to 150 seconds, if preheating is good, can press the "start" button, the end of the preheating time delay, and will be automatically saved in the preheat time delay parameters.

4. The cutting torch rise (perforation cutting up delay, M72).

5. Open cutting oxygen valve (M12), delay time, delay perforation after cutting down (perforation cutting delay M73).

6. Open the block (M38). Then began to run after the program.

Plasma cutting operation sequence is as follows:

M07

1. Cutting down (cutting down latency, see M71).

2. If you choose to perforation orientation (see parameter Settings) effectively, the cutting down, until the lower limit position switch, stop falling. After cutting, delay in holes positioning, stop cutting torch.

3. Open the arc switch

4. Detect "success" arcing voltage signal, if the parameter settings in the arc pressure detection from 0 (no) is any arc pressure, after the success of the arc, delayed perforation delay (in seconds).

5. Open the block (M38), began to run after the program

M08 concerns cut

Flame cutting fixed cycle operating sequence is as follows:

1. The concerns cut oxygen (M13).

- 2. Shut down the block (M39).
- 3. The cutting torch rise (M70).

Plasma cutting operation sequence is as follows:

- 1. The arc pressure switch.
- 2. Shut down the block (M39).
- 3. The cutting torch rises (M70).

M50 perforation action:

1. The cutting torch rise (M72), plasma operation without the action.

2. Open cutting oxygen (M12). Or open plasma arc, the detection of "success" arcing voltage signal.

- 3. Cutting down (M73), plasma operation without the action.
- 4. Open the block (M38).

M52 ignition fixed cycle:

Operating sequence: open gas (acetylene) valve (M10), high voltage ignition (M20), delays the ignition delay time, high voltage ignition (M21).

M70 cutting up fixed cycle:

Use the program starts, and a cutting end of the program, to raise cutting torch, so that the cutting torch fast move to the next cutting position. Sequence of operation: open cutting up switch (M14), delay cutting up delay (see 7.3) flame parameters, cutting up switch (M15).

M71 cutting down fixed cycle:

Used in punch, role, in contrast to the M70, but slightly smaller, because of the effect of gravity, than to hurry up.

Sequence of operation: open cutting down switch (M16), delay cutting down delay (see 7.3) flame parameters, cutting down switch (M17).

M72 perforation cutting up cycle:

Use after preheating, to raise cutting co., LTD., to avoid pulling cutting oxygen, splash of steel slag to block the mouth of the burning torch.

Sequence of operation: open cutting up switch (M14), delayed perforation cutting up delay (see 7.3) flame parameters, cutting up switch (M15).

M73 perforation cutting down cycle:

Use after preheating, performed M72, open after cutting oxygen, the cutting torch on the cutting position, is M72's action, but slightly smaller, because of the effect of gravity, than to hurry up.

Sequence of operation: open cutting down switch (M16), delayed perforation cutting down delay (see 7.3) flame parameters, cutting down switch (M17).

M75 cutting torch orientation delay:

Plasma rob positioning, cutting down (M16) first, when met the lower bit (see input port 8 XXW), stop cutting down (M17). And the burning torch up then (M14), after cutting positioning delay (see 7.4) plasma parameters, later, stop cutting up (M15).

M62 line drawing function:

After performing M62, cutting from the current position, offset a line drawing gun offset (see parameters setting function of the system). Since statements are function of line drawing, till the M63. When painting line does not perform slotting compensation function.

M63 end of line drawing function:

After performing M63, end of line drawing function, cutting from the current location, returns an offset line drawing a gun.

M80 terminal shut:

After executing M80 all outlet will be closed.

Chapter 7 Parameter Settings

In the system work under the main menu, press "F4", enter the parameter Settings interface, as shown in the figure below:



7.1 Parametric Description:

Speed parameters

The axis starting speed, adjusting time, highest speed limit;

System parameters

The shaft electronic gear ratio, the origin, reference point, the reverse clearance, line drawing bias, soft limit of positive/negative.

Flame parameters

Flame ignition delay, preheating time delay, cutting torch rise/fall time delay, punch cutting torch ascending/descending, perforated delay, etc.

Parameters of plasma

Cutting torch orientation delay, arc starting with M instructions, arc breaking with M, the choice of arc pressure detection, position detection, perforated delay.

Control parameters

Include flame/plasma mode selection, processing speed, edge notch choice, metric/inch selection, etc.

Storage capabilities

Modified parameters will be stored in the area.

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Note:

1) Selecting the above parameters, if the changes effective, needs to be stored separately, namely according to the "F8" storage.

2) Under the parameters of the main interface input password after "1928", "F8" save menu to factory Settings. At this point, the parameter changes will be stored in the factory Settings parameters, and the current user parameter. Upon initial parameters, the parameters are for the current factory. Otherwise, applies only to modify the current user parameters. After input password will pop-up menu, can choose to save the parameters to factory Settings **]** U disk save parameters **]** u disk import parameters **]** any functional operation.

3) One page shows no fewer than parameters, can use $\uparrow \quad \downarrow$ key line double check parameters.

7.2 parameter setting

In the parameter setup submenu, press [F1] key, enter the speed parameter setting function, as shown in figure 7.2:

UNITES:MILI	LIMETR	ES,SEC	OND		
STARTUP		0	0300		
TIMING(S)		(0.20		
CORNER ACCEL	ER(S)	(0.15		
HIGH SPEED		(04000		
MACHINING SP	EED(S)		0000		
RET ORIGIN S	PEED	(01000		
BACKWARD/FOR	WARD S	SPEED (0500		
SPD TRAN ANG	LE	0	035.00		
ESC SPEED	SYSTEM	FLAME	PLASMA	CONTROL	SAVE

Speed parameters include: Photos are for reference only.

Starting speed - system X, Y axles at the time of starting and stopping the speed (unit: mm or inches per minute, see control parameters, the same below).

Time adjustment - system by starting speed adjustment to the highest speed

(the speed) during the process of the time it takes. Unit: seconds.

Uniform acceleration time - In the process of add/deceleration, linear acceleration time is, usually slightly smaller than adjusting time (about nine over ten). Big machine this value accounted for the proportion of smaller.

Highest speed limit - the top speed for manual and execute commands G00 runtime (unit: MM or Inch/Min).

Processing speed limit - the highest in the manufacturing process of flame/plasma processing speed (unit: MM or Inch/Min).

Reset (back to mechanical zero) speed - reset (back to mechanical zero) (unit: MM or Inch/Min).

Back/forward speed - suspended back and forward operation specified speed

(unit: MM or Inch/Min).

Corner speed between conversions angle - when the program is running

direction change over this point, the system is the corner speed down to starting speed.

General system are heavier, this value is selected. Timing can be according to the tone, the processing speed and machine tool vibration condition. Vibration is big, this value is chosen small.



Running direction

The corner arc transition radius - see the corner.

Arc speed limit - only for the speed limit.

Corner radius arc transition radius, setting and the circular arc of the above the speed limit, when the arc radius is less than this value, according to the circular arc speed operation. The speed limit is set to 0, and arc function is invalid.

7.3 system parameters

In the parameter settings menu, press "F2" button to enter the system parameter setting function, as shown in figure 7.3:

UNIT	ES:MIL	LIMETR	ES,SEC	O N D			
NUMER	ATOR	Х	:0.000	0000	Y:0.	0000000	0 0
M/C O	RIGIN	Х	:-0010	. 0 0	Y : 0 1	00.00	
REFER	ENCE PO	DINT X	:0000.	0 0	Y : 0 0	00.00	
DRILL	OFFSE	rs x	:0000.	0 0	Y : 0 0	00.00	
CLEAR	ANCE	X	:0000.	0 0	Y : 0 0	00.00	
D I R - 0	RIGIN	X	:00		Y : 0 0		
SOFT	LIMIT+	Х	:09000	. 0	Y:09	000.0	
SOFT	LIMIT-	Х	:-0900	0.0	Y : - 0	9000.0	
RETUR	N SELE(CT:0-NC	RETUR	IN;1-P0	STTIVE	;-T-NE	GATIVE
ESC	SPEED	SYSTEM	FLAME	PLASMA	CONTROL		SAVE

Pulse equivalent - electronic gear molecules and the ratio of the denominator is

the pulse equivalent, unit microns, converted to X 1000 MM.

Pulse equivalent calculation formula = screw DISTANCE x 1000 / (360 x score/interval Angle x ratio).

The calculation method of pulse equivalent, adjustment method is as follows:

(1) The first rough set anpulse equivalent, example: 0.002.

(2) Points on the machine tool dynamic walking a standard distance (the longer the more exact), measure the actual walking distance, to the following formula:

Practical run distance / should run distance*original pulse equivalent=new pulse equivalent.

Make type reduction into the simplest fraction.

Example: at the beginning of pulse equivalent, example: 0.002, at 2000 mm, the actual 2651 mm.

$\frac{2651}{2000} \times 0.002 = 0.002651$

Machine origin - use connect into switch a special point on the set of machine

tools, machine tools without the use of mechanical origin, the origin of the machine tool can be set to zero. (Unit: mm or inch)

Reference point -- the starting point is defined as the process of machining, the

system is to run the program (G92) will be automatically generated. (Unit: mm or inch)

Reverse - due to mechanical connection with reverse clearance, clearance system

when reverses, it will compensate for clearance. Clearance value is obtained by actual measurement, unit: mm or inches. In general, not advocating a backlash.

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Core drill bias - punching or crossed gun relative to the cutting gun offset distance.

Reset direction - the system back to the direction of the mechanical zero, 1 negative, 0, nothing, 1 is reset.

Positive/negative soft limit - when the machine tool coordinate exceeds the soft plus or minus limit values set, alarm system, if when not in use, should be used

7.4 Flame parameters

to set the parameter is greater than the actual value.

In the parameter setup submenu, press "F3" button to enter the flame parameter Settings, as shown in figure 7.4:

UNITES:	MILLIMETE	RES, SEC	0 N D		
IGNITION			00.50		
HOTUP TIM	ME		000.0	7	
TORCHUP	FIME(M70)		02.00		
TORCHDN	FIME(M71)		01.80		
PIERCEUP	HIGH(M72)	01.00		
PIERCEDN	HIGH(M73)	00.80		
PIERCE T	IME		00.00		
OVER CUT	DELAY-TI	ME	00.50		
ESC SPI	CED SYSTEM	FLAME	PLASMA	CONTROL	SAVE

Ignition delay---flame cutting, when performing M20, open the high voltage ignition switch delay time.

Preheat delay---preheat-perforation time (unit: second), the preheating,

perforated began after preheating, if the preheating time is not enough, can press **L** pause **L**, preheating time delay automatically extend to 150 seconds, if preheating is good, can press the "start" button, the end of the preheating time delay, and will be automatically saved in the preheat time delay parameter.

Cutting up delay -- instructions that are executed (M70) - when the delay time of

auxiliary instructions (see 6.4 M), unit: seconds.

Cutting down latency M71-- instructions that are executed (M71) - when the

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delay time of auxiliary instructions (see 6.4 M), unit: seconds.

Punch cutting up -- instructions that are executed (M72) - when the delay time (see 6.4 M assisted instruction), unit: seconds.

Punch cutting down -- instructions that are executed (M73) - when the delay time of auxiliary instructions (see 6.4 M), unit: seconds.

Perforated delay -- When flame cutting punch performing M07, - after open the cutting oxygen delay, the cutting decreases.

Expired delay - shut down cutting oxygen, because of rest pressure in the pipe, through delay to next step, in order to improve the cutting surface finish.

Period of time delay --between processes in place after the line movement, via the time delay and then run the next line.

First open another cutting oxygen gun (0/1) - 0 - first rises the gun to open cut again choose 1 - start with cutting oxygen gun.

Use high pre M24 choosing (0/1) - plate punch, need to use high preheating

auxiliary, select this feature, open M24 preheating, shut down after preheating. Pay attention to, don't choose this, the whole process M24 don't open (hot). Gas use M instructions, open the outlet gas solenoid valve use address (see diagnostic function), if do not use (especially when answering system into the flame and plasma amphibious) to establish the M46.

7.5. Plasma parameters set

Set menu, press [F4] into the plasma parameter settings, as shown in figure 7.5:

UNIT	ES:MIL	LIMETR	ES,SEC	OND			
LOCATE	TE CHECK(0/1)						
LOCATE	LOGI	C (0-LC	G)	0			
TORCH	LOCATE	E TIME			00.5	0	
TORCHL	JP TIME	E(M70)			02.0	0	
TEMPO DESCENTE (M71) 01.80					0		
ARC-FE	ARC-FEEDBACK(0/1) 0						
MAX TIME FOR ARC-FEEDBACK(S) 10.0							
PIERCE TIME 00.30					0		
PARAMETER: 0 < P < 1 RETURN SELECT:0-NO RETURN:1-POSITIVE:-1-NEGATIVE							
ESC	SPEED	SYSTEM	FLAME	PLASMA	CONTROL		SAVE

Positioning detection of choice - when performing M07 instruction, select

whether to cutting positioning operation. 0-not position. 1-positioning operation.

Positioning detection logic (0 1 high/low) -- -- position switches normally open 0 (highly effective), normally closed (low effective) choose 1.

Cutting positioning delay

When plasma gun position, cutting down first. when met the lower bit, stop cutting down. And the burning torch up then, after cutting positioning delay stop cutting up (see M75 instruction), unit: seconds.

Cutting up delay M70-- instructions that are executed (M70) - when the delay

time of auxiliary instructions (see 6.4 M), unit: seconds.

Cutting down latency M71-- instructions that are executed (M71) - when the

delay time of auxiliary instructions (see 6.4 M), unit: seconds

Arc pressure test options -- In plasma operation, whether to detect arc pressure,

to make sure form this. (Choose 1) when detecting arc voltage, arc starting to detect when the arc voltage feedback, the runtime to monitor arc voltage feedback. When breaking arc voltage feedback, the system according to suspend processing, and the tip. The general plate processing arc pressure detection. Chose not to detect arc voltage (0). When the ignition switch opens, delay perforation began after processing delay, cutting process, don not detection of arc voltage feedback. The general sheet processing is not to choose arc pressure detection.

Punch time delay - when striking success after perforation delay system normal operation.

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Detect arc voltage maximum delay (in seconds) -- choosing arc pressure

detecting perforation, if after perforation time more than the "maximum delay", has not yet received successful ignition signal an error, suspend the current work waiting to be processed. After troubleshooting, press [start] to start perforation. The default is 60 seconds.

Perforated delay -- when strike success after perforation, delay system normal operation.

Punch for the first time delay - punch for the first time, because the gun is cold

so take a long time delay.

Arc, then open the water spray (0/1) -- table cutting machine, choose cylinder

control height, and sheet processing, need to open the water valve, select this option.

Positioning detection choice -- when performing M07 instruction, select

whether to cutting positioning operation, choose 1 for cutting positioning operation. The initial positioning of the wiring method willsee 10.6 when using plasma cutting typical wiring.

The corner -- shut up distance (corner) transformation in the procedures section,

may cause changes in the velocity of the (arc pressure would change, cause drop Gun), so the system automatically shut down when section at the end of the distance away by high control, unit MM.

Shut up speed -- shut down automatically when machining speed is lower than

this value higher, it is set to 0, and the function is invalid.

Distance from the finish off arc pressure -- processing is usually a close curve,

at the end of the process, start and end point come to together, tend to form the phenomenon of burnt, affect the finish. After selecting this distance, have the distance before the finish, and the automatic power off the arc pressure and higher.

Higher automatic signal delay (in seconds) -- --because when you start

cutting, arc voltage is not very stable, start cutting after the delay then open up automatically.

Arc starting with M instructions -- set up arc outlet, the default is M12.

Arc breaking with M instructions -- to break the arc set outlet, default is M 13.

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Note: when the arc breaking M instructions than arc M is big 1, indicating that they

are one outlet (even to open, and closed), the system controls arc starting switch use level control. When two M instructions are an even number, and are not equal, that is, two output control on and off operation respectively. The system control switches use pulse ignition control, pulse width 0.5 seconds.

7.5 control parameter set

In the parameter setup submenu, press "F5" button to enter the control parameter settings menu, as shown in figure 7.6:

UNIT	ES:MIL	LIMETR	ES,SEC	OND			
NUMER	ATOR	X	:000	00000	Y:0.	0000000	0 0
M/C O	RIGIN	Х	:-0010	. 0 0	Y : 0 1	00.00	
REFER	ENCE PO	DINT X	:0000.	0 0	Y : 0 0	00.00	
DRILL	OFFSE	rs x	:0000.	0 0	Y : 0 0	00.00	
CLEAR	ANCE	Х	:0000.	0 0	Y : 0 0	00.00	
D I R - 0	RIGIN	Х	:00		Y : 0 0		
SOFT	LIMIT+	Х	:09000	. 0	Y:09	000.0	
SOFT	LIMIT-	Х	:-0900	0.0	Y : - 0	9000.0	
PARAMETER: 0.00000001 < P < 1.000 RETURN SELECT:0-NO RETURN;1-POSITIVE:-1-NEGATIVE							
ESC	SPEED	SYSTEM	FLAME	PLASMA	CONTROL		SAVE

Flame (0)/plasma (1) choice - select 0 when choose a flame processing, plasma process selection 1.

Automatic speed change rate - automatically adjust the speed when the rate of change.

Edge notch choice (0/1) - 0 means don't choose edge of perforation, 1 means choose edge notch.

Steel plate to X width X direction, steel plate width actually, this parameter is only running in heavy work.

Steel sheet to width Y--- The Y direction of the actual height, this parameter is only runs in large work.

Total XZ: 0 / YZ: 1 choice -- because the system can control three axis movement, for there is a requirement for bilateral drive machine, third axis is edge,

with the X axis and Y axis side, in the choice. Choose 0, Z axle with the X axle total side. Choose 1 Z axle and Y axle side.

Inch/metric: 0:1 choice - metric: 0 length parameters, speed, and the value, the

coordinates are metric unit (MM), processing English program (G20), but the display is a metric unit (MM). Option 1 inch: parameters, display, coordinates are imperial units (inches), processing metric program (G21), but the display is imperial units (inches).

Calculation accuracy, programming, some nesting software will generate a little burr, set this parameter can be ruled out, the default value is 0.1 MM.

Take over control box to choose (0/1) -- if you use the outside to take over

control box, choose 1, otherwise 0.

Wired/wireless remote control to choose (0/1) -- took over control box is

wired remote control to choose 0, wireless remote control to choose 1.

G41 / G42 test effective (0/1)– System compensation of validity check (G41 / G42) is correct. When the error is not serious, chose this parameter 0, prompt error line, but don't call the ring, the program can continue.

Choosing processing clean coordinates (0/1) - option 1, before processing,

automatic will coordinate to 0. WENTAI(carved) software without G92 instructions for this function.

Cutting air (0/1) - sheet processing, using pneumatic lift than automatically

adjustable high effective, optional 1, otherwise 0. Choosing pneumatic elevation, cutting down the M16, effectively cutting torch rise M16 invalid (cancelled).

Processed automatically back to choose (0/1) - option 1, processing after

the automatic back to the reference point. External limit effective (0/1) - many small cutting machine for easy without external hard limit, can choose [parameter] - [control] - external limit effective = 0, in order to avoid unnecessary hard limit alarm of failure.

Software limit effectively (0/1) - option 1, soft limit function to take effect.

Bump shot detection (0/1) - if the equipment is equipped with effective bump

shot detection (P1 feet using positive limit input port), optional [parameter] - [control] - bump shot detection effectively = 1, the input normally closed connection, in case of collision gun (off), immediately suspend (and submitted to the gun warning).

Note: when using the bump shot detection, must cancel, hardware limit function.

Hit gun with localization testing whether a detecting and locating detection (0/1) -

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the wall is the same input port selection.

Hit gun after the suspension of operation (0)/rise gun (1) - 0, bump shot suspended after processing, choose 1, gun automatic after, processing to continue.

Suspended after rising gun (0/1) after choice - if you want to stop, have carried cutting action, optional choose suspended after rising gun = 1.

Cutting length (broken bridge point. MM) - processing when choosing broken bridge function, each cut the length, will automatically set up a broken bridge point.

Broken bridge length (MM) - setting, middle-east blank lines after this distance (bridge) wide, to start cutting.

The main screen text (0/1) - whether under the boot screen, display the text information of the company, this text under the main interface, press GG8 modification.

Option to show slotting compensation line (0/1) - whether display slotting compensation after the coordinates of the track.

Note: when did not understand the parameters of concrete application, please carefully change!

Chapter 8 the gallery features

8.1 Graphics library setup:

Input to the size you want, to get what you need to artifacts.

When the input parameters, control system general inspections of geometry size, there is an error to display warning information.

Note:

1) The control system can't check all of the error parameters, as much as possible to input the correct size parameters.

2) When you input parameters, the parameters of the control system will be based on the input automatically draw the graphics. This examination is helpful for graphics. Working in the system under the main menu, select the "F6" into the gallery.



8.2 the select ion of graphical parts

At present this system provides 24 graphic unit (can be readily expanded according to customer requirements), press the direction key [up] [down] [left] [right] mobile highlight cursor, choose the required graphics, press "ENTER" key to confirm.

8.3 set of graphical parts and discharge

After the parts according to the last steps selected, upper prompts for various parameters of graphics. As shown in figure 8.2:

[F1] Artifacts: according to the work piece machining (for effective parts).

[F2**]** Hole shape: according to the hole shape processing is made valid by means of the (outside).

[F3**]** Rotation: system prompts for rotation Angle and press [ENTER] or F6 submit, display graphics after the rotation. Angle counterclockwise is positive.

[F4**]** Arrange material : system prompts input.

Number of lines - array processing line Numbers.

The number of columns - arrange the job number of columns.

Line spacing - the distance between line and line.

Column spacing – The landscape distance of processing pieces

Line offset - interlaced dislocation of the offset. As shown in figure 8.3 schematic diagram:





Graph 8.3 Layout diagram

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Chapter 9 diagnostic function

In the system work under the main menu, press "F5" button to enter diagnostic function main interface, as shown in the figure below:

110	M12	M14	M16	M38	M20	M22	M24
0	0	0	0	0	0	0	Θ
IT :							
WP	L₩N	S X O	S Y 0	DLZ	ST0	PAS	LD₩
1	1	1	1	1	1	1	1
SXP	SXN	SYP	SYN	PRE	SPP	SPN	CHE
1	1	1	1	1	0	0	0
9 17:2	9:16						
138	M12	M14	M16	M 1 0	M20	M22	M24
0	0	0	0	0	0	0	0
IT:							
WP	L₩N	S X O	SYO	DLZ	ST0	PAS	LD₩
.₩P 1	L₩N 1	SX0 1	S Y O 1	DLZ 1	ST0 1	PAS 1	LD₩ 1
.₩P 1 SXP	L₩N 1 SXN	SXO 1 SYP	SYO 1 Syn	DLZ 1 PRE	STO 1 SPP	PAS 1 SPN	LDW 1 CHE
WP 1 SXP 1	LWN 1 SXN 1	SX0 1 SYP 1	SY0 1 SYN 1	DLZ 1 PRE 1	STO 1 SPP 0	PAS 1 SPN 0	LDW 1 CHE 0
WP 1 SXP 1	L₩N 1 SXN 1	SX0 1 SYP 1	SY0 1 SYN 1	DLZ 1 PRE 1	STO 1 SPP 0	PAS 1 SPN 0	LDW 1 CHE 0
	0 T: WP 1 3XP 38 38 0 T:	0 0 1 : WP LWN 1 1 5 XP SXN 1 1 0 17:29:16 138 M12 0 0 17 0	0 0 0 1 1 1 1 1 1 5XP SXN SYP 1 1 1 0 1 1 0 1 1 0 0 0	0 0 0 0 1 1 1 1 1 1 1 1 5XP 5XN 5YP 5YN 1 1 1 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 <td< td=""><td>0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 2 5XN SYP SYN PRE 1 1 1 1 1 2 1 1 1 1 3 M12 M14 M16 M10 0 0 0 0 0</td><td>0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 2 SXN SYP SYN PRE SPP 1 1 1 1 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 1 1 1 0<td>0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 2 SXN SYP SYN PRE SPP SPN 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 1 1 0 1 1 1 1 1 0 0 0 1 1 1 1 1 0 0 0 0 1 1 1 1 1 0 0 0 0 0 0</td></td></td<>	0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 2 5XN SYP SYN PRE 1 1 1 1 1 2 1 1 1 1 3 M12 M14 M16 M10 0 0 0 0 0	0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 2 SXN SYP SYN PRE SPP 1 1 1 1 0 0 0 0 1 1 1 1 0 0 0 0 0 1 1 1 1 1 0 <td>0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 2 SXN SYP SYN PRE SPP SPN 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 1 1 0 1 1 1 1 1 0 0 0 1 1 1 1 1 0 0 0 0 1 1 1 1 1 0 0 0 0 0 0</td>	0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 2 SXN SYP SYN PRE SPP SPN 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 0 0 1 1 1 1 1 1 0 1 1 1 1 1 0 0 0 1 1 1 1 1 0 0 0 0 1 1 1 1 1 0 0 0 0 0 0

9.1Input/output interface check

System diagnosis according to the current system of open hardware resources, under the system diagnostic images, can check the input/output interface.

9.2 output check

Every outlet only defines the M address (instruction), move the cursor to the photoelectric isolation at 8 output at any position, with "0" and "1" to change the

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output level. Setting 1, 0 means canceled. See the output each port definitions (input/output port definition).

9.3 input inspection

It shows the current photoelectric isolation input state. 0 means low potential (ground), 1 said the port high potential (24 v or hung up). Its input symbol definition can see ports (input/output port definition).

Input diagnosis:

LWP - external is limit (normally closed switch), choosing bump shot detection, the foot a gun testing point.

LWN - external negative limit (normally closed switch).

SX0 / DUP - has two functions, reset direction is valid is X0 mechanical original, it is an external manual, cutting up switch (no lock, normally closed connection).

SY0 / DDN, has two functions, reset direction is valid is Y0 mechanical origin, it is an external manual, cutting down the switch, no lock, normally closed connection).

DLZ - plasma arc mouth (arc starting signal success) measurement, low effective.

STO - external abrupt stop switch (normally closed connection). PAS - external pause switch (normally closed connection).

LDW -before the initial positioning of plasma perforation

SXP SXN SYP SYN PRE - is an external wireless remote control coding input. SPP SPN CHE - useless interface.

Chapter 10 System input/output interface connected

The system interface: including input/output (DB25 core), the motor (15 core), a wireless remote control (15 core), meet the company production of block.

10.1 the system input principle

Generally limit/start/stop using mechanical switch, to prevent interference to enter, usually use the normally closed contact of a mechanical switch, according to the chart mode connection.



Note:

System requires urgent stop, pause, the logic is consistent, namely by normally open or connected normally closed points (common).

System boot automatically detects the external trigger a state, as a control.

So, if you do not answer the external start switch, the corresponding bit should be received 24 V (similar to answer the normally closed contact) or what all don't pick up (similar to connect normally open contacts).

10.2 the principle of the system output:

Control signal = 0 switch/relay connected (24 V loop formation, low effective signal) Control signal = 1 switch/relay disconnect (24 V did not form a loop, cancel)



10.3 Input/output connect definition

Signal Definition	25core (hole)		Illustration
>W	1	Input	X/Y + limit, two axes is limit concatenated, high effective. If you don't use, please send short signal received 24 V, if do not use the limit, it is a bump shot detection (normally closed)
W <	14	Input	X/Y - limit, limit concatenated two axles, high effective. If you don't use, please send short signal received 24 V.
SXD/ DLP	2	Input	XD mechanical origin, NPN proximity switch, normally is open. Reset the direction is invalid when the mouth for external cutting up key, high effective, if you don't use, please send short signal received 24 V.
SYO/IIN	15	Input	YO mechanical origin, NPN proximity switch, normally is open. Reset direction is invalid when the mouth as external cutting down key, high effective, if you don't use, please send short signal received 24 V.
DEZ	3	Input	Detect arc voltage, low effective and high arc pressure when not connected to.
STO	16	Input	External scrambutton and high effective, if you don't use, please send short signal received 24 V.

PAU	4	Input	External pause button, high effective, if you don't use, please send short signal received 24 V.
XXW	17	Input	A plasma cutting torch orientation, the lower limit.
	5	Output	Raised corner signal (higher automatic/manual switch) relay normally open contact
	18	Output	Output signal relay ignition normally open contact
	6	Output	COM (OHL / OH2 OHB / OH4 relay) to isolate the outputpublic side of adjustable
	19	Output	Block cutting torch (OH2) normally open reduction is set
	7	Output	Block cutting torch (OHB) 1 normally open tuning
	20	Output	Block cutting torch (OH4) normally closed reduction is set
	8	Output	Block cutting torch (OHB) rose normally closed
M0/M1 or M88/M89	21	Output	Flame: M88 higher control M88, M89 close Plasma: M0 standby M0, M1 close
M20/ M21	9	Out put	M20 (open), M21 (closed), fire mode, used in the ignition switch. Plasma model, when the ignition delay time of 0, is always open (switch) as a function of flame/plasma
M22/M23	22		Spare
M4/M5	10		Spare
	23	Output	Corner (OH) normally closed
	11	Output	Cutting oxygen (OH2) normally closed
24V	24	Output	+ 24 V/1A
24V	12	Output	+24V/1A power supply
24 V地	25	Output	24V power supply ground
24V地	13	Output	24V power supply ground

10.415 core motor port definitions

1) Differential signal (2) a total of anode connection



10.5 when using flame cutting typical wiring (DB15)



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10.6 when using plasma cutting typical wiring

10.7 flame/plasma sharing processing

When plasma/flame, plasma by plasma, flame in flame, you also need to pick up a choice of flame/plasma switch K1, connection as shown in the figure below.

(1) The KR acetylene (gas) solenoid valve.

(2) The KQ cutting oxygen solenoid valve.

(3) If the acetylene (gas) solenoid valve is not answer, gas contact cannot meet.

(4) The K1 for flame/plasma select relay (M20).



10.8 form a complete set of peripherals connection definition 10.8.1 the

company adjust block (SF - HC30) 15 core joint pindefinition

10.8.2 system communication/manual XS8 (DB15) connection definition

Number	Definition	Illustration	Connent
1	Serial port public	232- COM	
2	Serial portreceive	232- RD	
3	Serial port send	232- TXD	
4	Input signal	Arc pressure (the height of the cutting head)	
5	Signal	Signals of arc voltage	
7.14	Power supply	24 V power supply is, highly controller in	
8 15	Power supply	24 V power supply, high power supply	
10	Input	Minual/automatic selection signal controller	
12	Input	Minual up signal, drive the cutting head up	
13	Input	Minually down signal, driving down cutting head	

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Number	Definition	Illustration	Connent
1	24V	24V power	
2	TXD	RS232 send	
3	RXD	RS232 receive	
5	СОМ	RS232 public	
9	18	Input port 9 and can be used for wireless control box	
10	19	Input port 10 and can be used for wireless control box	
11	I 10	Input port 11 and can be used for wireless control box	
12	I11	Input port 12 and can be used for wireless control box	
13	112	Input port 13 and can be used for wireless control box	
8、15	24G	24V Power	

Appendix 1: this company produces the block SF - HC30 wiring diagram and pin definition

1. The arc pressure type, capacitance type using a mixture of wiring diagram



2. 9 points platen core joint pin definition table

Number	Attribute	Illustration
2	Power supply	24 V power supply, high controller supply
5	Power supply	24 V power supply, high controller supply
6	Output	Arc height controller pressure signal, the height of the plasma cutting head

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9	Power supply	24 V power supply, high controller supply

3. The arc voltage tuning block diagram



connect to high controller

connect to cnc controller

4. Capacitance call block diagram



Flame pattern wiring diagram

Highly controller side

CNC controller side

Appendix 2: SF - RF06 wireless hand control box

Type SF - RF06 wireless hand control box, using 2.4 GHz radio frequency transmission and six digits and 3 addressing encryption technology to realize remote control of CNC system. A total of 22 on the remote control buttons, it contains forward back to walk around and start pause, all high voltage control function.



The wireless remote controller Effective distance 30m CNC controller

Key Illustration

Number	Key name	Key function
1	I	Start
2	0	Suspend
3	Perforated	Perform a complete action to on the perforation
4	Gas	Open the gas switch
5	Arc start ing	Open cutting oxygen (plasma) switch
6	Back	During processing, suspended after the original track back
7	Forward	Aftersuspend processing to move forward
8	Always	Cut off all of system control output
9	Shut up	M38 control
10	S+	Guns rise control
11	S-	Guns lowered control
12	F+	Welding speed (cutting), power (current) increase control
		key
13	F-	Welding (cutting) speed, power cut control keys (current)
14	#	Forward
15	\$	Back
16	!	Turn left
17	"	Turn right
18	~	Gun head X-, Y+ move
19	7	Gun headX+, Y- move
20	1	Gun head X+, Y+ move

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21	4	Gun head X -, Y- move
22	∽	Feed ratio fast adjustment, press the 5%, press the 80%
		again

Wiring definition

CNC SF-21006 DB15		Vireless hand control box DB15core	
Pin	Pin	Pin	Pin
Number	Definition	Number	Definition
1	24V	1	24V
8	24G	8	24 G
9	I8	9	S1
10	I9	10	S2
11	I10	11	\$3
12	I11	12	S4
13	I12	13	\$5
15	24G	15	24 G

Size: (135 * 55 * 16 MM) remote control receiver installation size chart:



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Appendix 3: SF-2100S-AH software upgrade instructions

Function: system can through the U disk, implementation program to upgrade.

Specific operation is as follows:

1. The update file

Copythe upgrade file 'STARTCNC. EXE to the USB drive.

2. The steps

With your fingers hold down system is the key on the front panel. Turn on the power to the system power on, waiting for system upgrades its interface display screen appears, then to loosen the button.

After inserted U disk, press screen below the F1 key (that is, the screen of the "upgrade" button on the menu), the system will automatically upgrade operation.

3. Upgrades end

If update program successfully, the system will prompt "upgrade success!" And the buzzer will ring.

If program upgrade failure, the system will prompt "upgrade failed!" And the buzzer will ring continuously.

4. Start the new program

Shut off the power and pull out U disk, open the power supply can start the new program. The boot screen will be displayed after the new version of the program. Note: if the upgrade is not successful, please check the following factors:

The U disk must be FAT or FAT32 format. The proposal had better use FAT format.
 Upgrade file name must be STARTCNC. EXE.

3) The upgrade file must be put in U packing directory.

4) Such as in the process of upgrading, did not appear the prompt of the upgrade is complete and updated directly back to the main interface, or upgrade failure caused by other accident.

But first check upgrade file name is correct, U disk, format is correct; When the elimination of the upgrade file and U disk.

After the two factors can be carried out in accordance with the specific operation steps again upgrade operation.

If attempts to upgrade still fail, please call customer service to Beijing STARFIRE control technology co., LTD.

Appendix 4: install size figure







Fault phenonenon	Failure analysis	Deal way
To stop work in the sam position every tim processing	1. Process problem 2. CNC system software has a problem	Send back program, analysis by designers.
Michine to stop vorking, the system normal operation, and the burning torch stopped or just a shaft vork	1. Traveling notor blocked 2. Wilking notor fault	Check whether the nachine is stuck put smooth
When the machine stops vorking, work system cutting valking along a certain direction or not go, and press any key (especially the pause button) doesn't work	Michine tool interference crashing	 a. Remove interference - note the machine plasma power grounding with machine. b. Mitor (old system) and isolation plate c. Flame way, pay attention to the cutting oxygen switch electromagnetic valve is plus arcing processing.
Motor is not running	Systemwiring loose or fall off Drive has set alarmdisplay System startup is zero or too much, control time is too short, electronic gear or pulse equivalent.	Connect again Midify driver setting Change drive settings, record before modification suggestions to the original parameters
Systemresponse slow	Switching power supply output voltage is not permitted within the scope of action Systemparameters is not correct	Adjustment switch power supply output voltage or replace Change system settings (before modification request to the original parameters for recording).
Boot appear linit aları	The linit switch is not normal Connecting virtual fall off on excessive Current coordinates system beyond the linit value	Repair or replace the limit switch Connect again Changes to normal range
	Beyond the software limit value	Have reset

The appendix 5: common troubleshooting

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		To see if the corresponding	
	External dovice or coftuero	innet met stata uithout	
	exercise device of solution	change screen after the	
	systemment	renair or renlacement	
		First recorded in the system	
		rist recorded in the system	
		first, then the system hain	
	Parameters setting incorrect	interface, in turn, first	
		press the G, G, and 3, the	
Minual and automatic		second into the parameters	
crash		set to save, restart the	
		system will note down the	
		electronic gear value fill in	
		the corresponding position,	
		storage parameters after	
		comissioning	
	Input and output wiring loose or	G	
	fall off	Connect again	
	24 V nower supply is not normal (25		
Input\Output nothing	core voltage) between the 24. 25	Repair or replace power	
	feet of the interface	adapt er	
Display not normal	Systemdanage (excent escalation		
	cases)	Repair or replace	
		Penlace the other type or	
	U disk and the systemcan't natch	heptake the other type of head of II disk	
		Decouver for FAT forward	
USB INCEPTACE ODES NOU	Ine U disk in the wrong format	Netornal for fal fornal	
transfer	Systeminternal loose connection	l To reconnect, clear interface	
	or USB port or pin of different	sundry	
	body in it.		
Process starts,	If no longer amears, can evolain	Check program	
automatic return to the	the moredure of this median		
n a in interface			
System can only be		Initialization of system	
opened machining line		paraneter	
cannot be the whole round Solenoid valve or plasm arc screen flash		Check or send back the	
	If normal, check the program	department	
		Put the plasma nower comply	
	Placm novor cumly cyctom	system machine shell and	
	nachim choll uithaut a tatal	competed to the south	
	namentar saria wetatuk a total	commetter to the earth,	
	gru n		
		should be greater than 2mm ² ;	

		Systeminut, autuut, use the
	Systemofinant and output, no use	shielded wire, and the thrun
	the shielded wire.	of the exposed part is not greater than 30 mu
	Do not use the input no grounding power	Will not use the 24 V input and ground short connection.
		Between 24 V earthed and the shell (i.e., shielded wire) plus a 0.01 uF capacitance
		Add isolation transformer (380 V ~ 220 V) and interference suppressor.
	Power supply loose connection each other	High power welding machine/cutting machine working power supply should be separated from systen power supply.
Programcannot store o garbled	r	Under the main menu, press GG 3, select the file format, operation after the shutdown, restart again.
System output point is invalid	24 V power supply danage or loose connection each other (masure the voltage between 24 and 25 feet)	Replace power adapter, or connection again.
	Systemback relay installed loose or danaged (the relay operation is normal, contact is valid).	To install relay or replacement